Solution 9

Supplementary Problems

1. Let $F = (F_1, \dots, F_n)$ be a smooth vector field in an open region in \mathbb{R}^n . Show that if it is conservative, then the necessary conditions hold

$$\frac{\partial F_i}{\partial x_j} = \frac{\partial F_j}{\partial x_i} , \quad \forall i, j.$$

Solution. Let $F = \nabla f$. Then

and

$$\frac{\partial F_j}{\partial x_i} = \frac{\partial}{\partial x_i} \frac{\partial f}{\partial x_j},$$

 $\frac{\partial F_i}{\partial x_j} = \frac{\partial}{\partial x_j} \frac{\partial f}{\partial x_i},$

so they are equal. When n = 3, this reduces to the usual compatibility conditions (or necessary conditions, or component test):

$$M_z = P_x, \quad M_y = N_x, \quad N_z = P_y \;.$$

- 2. A region is called star-shaped if there is a point O inside so that the line segment connecting any point in this region to O lies completely in this region. For simplicity take O to be the origin.
 - (a) Show that in case the vector field \mathbf{F} admits a potential g in this region, then

$$g(x, y, z) = \int_0^1 \mathbf{F}(tx, ty, tz) \cdot (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) dt$$

(b) Show that when \mathbf{F} passes the component test, the above formula defines a potential function for \mathbf{F} .

Solution. (a) We will work on the general dimension, so $\mathbf{F} = (F_1, F_2, \dots, F_n)$. By Chain Rule we have

$$\frac{dg}{dt}(tx_1, tx_2, \cdots, tx_n) = \frac{\partial g}{\partial x_1}(t\mathbf{x})x_1 + \frac{\partial g}{\partial x_2}(t\mathbf{x})x_2 + \cdots + \frac{\partial g}{\partial x_n}(t\mathbf{x})x_n$$
$$= F_1(t\mathbf{x})x_1 + F_2(t\mathbf{x})x_2 + \cdots + F_n(t\mathbf{x})x_n .$$

Therefore,

$$g(x,y) - g(0,0) = \int_0^1 \frac{dg}{dt} (tx_1, tx_2, \cdots, tx_n) dt$$

=
$$\int_0^1 F_1(t\mathbf{x}) x_1 + F_2(t\mathbf{x}) x_2 + \cdots + F_n(t\mathbf{x}) x_n dt$$

=
$$\int_0^1 \mathbf{F}(t\mathbf{x}) \cdot \mathbf{x} dt .$$

We are done after setting g(0,0) = 0.

(b) In a general dimension, the component test becomes

$$\frac{\partial F_i}{\partial x_j} = \frac{\partial F_j}{\partial x_i} \;,$$

for different $i, j = 1, 2, \cdots, n$. With the above formula for g,

$$\begin{aligned} \frac{\partial g}{\partial x_i} &= \int_0^1 \left[\frac{\partial F_1}{\partial x_i}(t\mathbf{x}) tx_1 + \frac{\partial F_2}{\partial x_i}(t\mathbf{x}) tx_2 + \dots + \frac{\partial F_n}{\partial x_i}(t\mathbf{x}) tx_n + F_i(t\mathbf{x}) \right] dt \\ &= \int_0^1 \left[\frac{\partial F_i}{\partial x_1}(t\mathbf{x}) tx_1 + \frac{\partial F_i}{\partial x_2}(t\mathbf{x}) tx_2 + \dots + \frac{\partial F_i}{\partial x_n}(t\mathbf{x}) tx_n + F_i(t\mathbf{x}) \right] dt \\ &= \int_0^1 \frac{d}{dt} tF_i(t\mathbf{x}) dt \\ &= F_i(t\mathbf{x}) \Big|_0^1 \\ &= F_i(\mathbf{x}) \;. \end{aligned}$$